
Siemens Simovert via USS

Application Note

This document contains specific information regarding the use of Red Lion's communications driver for Siemens Simovert via USS protocol. The communications protocol supports access to pertinent parameters. Please read this document carefully before attempting to configure communications with these devices.

Accessible Data

| Prefix | Description | Element Size | Minimum | Maximum |
|--------|----------------|--------------|---------|---------|
| P | Parameters | 16 bits | 0 | 999 |
| STW* | Control Word | 16 bits | N/A | N/A |
| HSW** | Frequency Word | 16 bits | N/A | N/A |

* The STW field is used to control the operation of the converter. Each bit is as defined below.

| STW – Control Word Field | | | |
|--------------------------|-------------------|--|--------------------------------------|
| Bit | Definition | Disabled | Enabled |
| 0 | OFF1 | Activates the OFF1 condition | Allows the inverter to run |
| 1 | OFF2 | Activates the OFF2 condition | Allows the inverter to run |
| 2 | OFF3 | Activates the OFF3 condition | Allows the inverter to run |
| 3 | RUN | Switches the inverter output off immediately | Allows the inverter to run |
| 4 | Fast Stop | Decelerates the inverter as fast as possible along the DC Link Voltage | Allows the inverter to run |
| 5 | Ramp Hold | Holds the ramp rate generator at its present frequency | Allows the inverter to ramp normally |
| 6 | Ramp Inhibit | Ramp to 0.0 Hz | Ramp normally |
| 7 | Fault Acknowledge | Clear the inverter from a tripped or fault state | |
| 8 | Jog Right | No action | Jog Right |
| 9 | Jog Left | No action | Jog Left |
| 10 | Control Valid | Ignore control bits | Control bits are valid |
| 11 | ON Right | No action | Requested direction is right |
| 12 | ON Left | No action | Requested direction is left |

** The HSW contains the desired frequency demand to the inverter. This demand is scaled such that a value of 4000H represents 100%. The scaling is set in a parameter on the inverter. For inverter specific information, please refer to the appropriate inverter manual.

Sending Commands

The Control Word (STW) and the Frequency Word (HSW) are used to send commands to the inverter. The following steps should be taken to send all commands:

- 1) Set STW to the appropriate value (as defined in the chart above) for the desired inverter behavior.
- 2) Set HSW to the appropriate value.
- 3) Write a non-zero value to SEND (Send Command) in order to initiate the command.

Please note if no value is needed for the HSW field for the command being sent, the HSW must always be set to 0 before SEND is written.

Sending Commands - Examples

Example 1: Run Inverter at 50% frequency.

- 1) Set STW to 0x0C7F.
- 2) Set HSW to 0x2000.
- 3) Write a non-zero value to SEND (Send Command).

Example 2: Immediately switch inverter off.

- 1) Set STW to 0x0C7D.
- 2) Set HSW to 0x0000.
- 3) Write a non-zero value to SEND (Send Command).

Broadcast

Designate a PLC drop number of 32 in order to broadcast a command to all inverters on the loop.

Default Communication Settings

The default configuration for the Siemens Simoververt via USS driver is as follows:

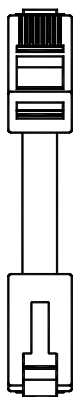
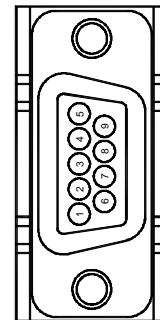
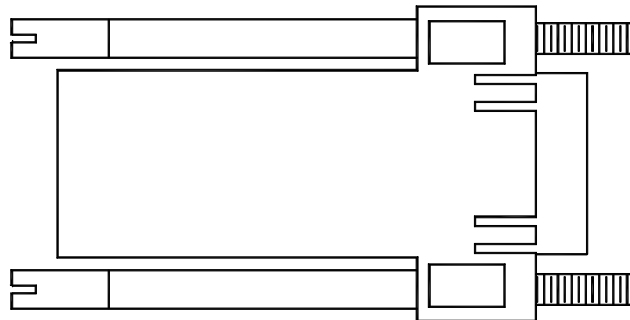
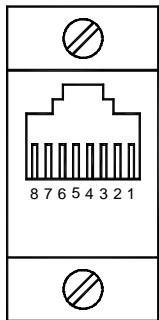
| | |
|----------------|-------|
| Port | RS485 |
| Baud Rate | 9600 |
| Data Bits | 8 |
| Parity | Even |
| Stop Bits | 1 |
| Device Address | 1 |

Knowledge of Unit Operation Is Assumed

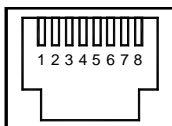
In all cases, the simple principle of 'pass-through' is maintained: there is no attempt to validate a value in terms of the end use of the unit: both familiarity with the Drive functions and knowledge of system operation are assumed.

Communications

The connection details are described in the table below.



| Connections | | | |
|---------------|------|------------------|----------|
| FROM RLC UNIT | Name | CONNECTER PINOUT | |
| | | RJ45 | DB9 MALE |
| 1 | TxB | 1 | 3 |
| 2 | TxA | 2 | 8 |
| 3 | RxA | 3, 8 | - |
| 4 | RxB | 4, 7 | - |
| 5 | TxEN | 5 | - |
| 6 | COMM | 6 | 5 |
| 7 | TxB | 4, 7 | - |
| 8 | TxA | 3, 8 | - |



RS485 PORT
(FROM RLC UNIT)

The above table denotes the pin names of the RS485 port. When connecting, the pin name at the RS485 port is connected to the opposite of that pin name at the destination device.