

# **Giddings and Lewis C/E Controller**

# **Information Sheet for Crimson v2.0**

#### **Compatible Devices**

Giddings and Lewis C/E Controller

#### **Verified Device**

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**NOTE:** The driver does not verify the correctness of any data sent to the drive. It is the programmer's responsibility to ensure that written values are within safe limits. **NOTE:** Items preceded by "..." must be loaded with valid values before the IEXE, PEXE, or CEXE command, as appropriate, is executed.

**IMPORTANT:** Except for DV, a value shown when reading a selection is not valid until it has been written. The programmer is responsible for restoring correct values to write-only selections subsequent to a download, or power cycle.

#### **Accessible Data**

Mnemonic	Description	Notes
IEXE	EXECUTE Initialization( I )	1
ISEL	Selector	2
IPHS	Phases	2
IBS1	<unused></unused>	2
IBS2	<unused></unused>	2
ISO	Stabilizer Offset	2
IFFO	Forward Frontstop Coarse Offset	2
IWO	Whip Offset	2
INO	Nip Offset	2
IRFO	Reverse Frontstop Coarse Offset	2
IDSP	DS Side Guide Position	2
IOSP	OS Side Guide Position	2

Mnemonic	Description	Notes	
PEXE	EXECUTE Position Update(P)	3	
POIP	C/E Offset In Position	4	
POP	C/E Offset Position	4	
PSC	Status Code	5	
PFL1	Flag Word 1	5	
PFL2	Flag Word 2	5	
PFL3	Flag Word 3	5	
PWR	Whip Resolver 5		
PFFR	Frontstop Fine Resolver 5		
PFCR	Frontstop Coarse Resolver	5	
PSR	Stabilizer Resolver	5	
PNR	Nip Resolver	5	
POSR	OS Side Guide Resolver	5	
PDSR	DS Side Guide Resolver	5	
PWP	Whip Position	5	
PFP	Frontstop Position	5	
PSP	Stabilizer Position	5	
PNP	Nip Position	5	
POSP	OS Side Guide Position	5	
PDSP	DS Side Guide Position	5	
CEXE	EXECUTE Send Commands( C )	6	
CBCT	Bundle Count	7	
CUO	Ups/Outs	7	
CBCL	Board Caliper	7	
COC	Offset Command	7	
CWC	Whip Command	7	
CFC	Frontstop Command	7	
CSC	Stablilizer Command	7	
CNC	Nip Command	7	
COS	OS Side Guide Command	7	
CDS	DS Side Guide Command	7	
SS	Stop Setup(S)	8	
DV	R/W Downstacking Value( K/k )	9	
SSV	Send Spanking Value(s)	10	

# NOTES:

# Initialization (I):

- Setting **IEXE** to a non-zero value will send the initialization data to the controller.
  The programmer must ensure all "I" values are valid before executing **IEXE**.

#### **Position Update (P):**

- **3)** Setting **PEXE** to a non-zero value will send **POIP** and **POP** to the controller, and store the response for each item **PSC** through **PDSP**.
- **4)** The programmer must ensure valid data is contained in **POIP** and **POP** before executing **PEXE**.
- **5)** The data retrieved by a **PEXE** command is stored in the driver. Any item may be requested, but is only updated when the **PEXE** command has been issued.

# **Send Commands (C):**

- **6)** Setting **CEXE** to a non-zero value will send the command data.
- 7) The programmer must ensure all "C" values are valid before executing CEXE.

# STOP SETUP (S):

**8)** A non-zero value written to **S** will send the Stop Setup Command.

# **DOWNSTACKING VALUE (Read = K, Write = k):**

**9) DV** is the <u>ONLY</u> item that can be read and written.

# **SEND SPANKING VALUE (s):**

**10)** Writing a value to **SSV** sends the number to the controller. That number is also stored within the driver. The most recently written value is returned when a read of **SSV** is done.

# **Cable Information**

#### **RS232 Serial Connection**

C/E	Signal Name	G3
2	Tx >> Rx	2
3	Rx << Tx	5
5	0V	3/4